

Mathematical Methods in Physics HW7

1. Consider polynomials on the interval $x \in [0, \infty)$ with inner product $(f, g) = \int_0^\infty f^*(x)g(x)e^{-x} dx$.

- a) Gram-Schmidt the linearly independent set $\{x^0, x^1, x^2, \dots\}$ to find the first three orthonormal polynomials $\hat{L}_n(x)$.

$$\hat{L}_0(x) = \frac{x^0}{\|x^0\|} = \frac{1}{\|1\|} = \frac{1}{\sqrt{(1,1)}} = \frac{1}{\sqrt{\int_0^\infty 1e^{-x}dx}} = 1$$

$$\hat{L}_1(x) = \frac{x - \hat{L}_0(\hat{L}_0, x)}{\|x - \hat{L}_0(\hat{L}_0, x)\|} = \frac{x - 1}{\sqrt{\int_0^\infty (x-1)^2 e^{-x} dx}} = x - 1$$

$$\hat{L}_2(x) = \frac{x^2 - \hat{L}_1(\hat{L}_1, x^2) - \hat{L}_0(\hat{L}_0, x^2)}{\|x^2 - \hat{L}_1(\hat{L}_1, x^2) - \hat{L}_0(\hat{L}_0, x^2)\|} = \frac{x^2 - (x-1)(4) - 1(2)}{\|x^2 - (x-1)(4) - 1(2)\|} = \frac{x^2 - 4x + 2}{\sqrt{\int_0^\infty (x^2 - 4x + 2)^2 e^{-x} dx}} = \frac{1}{2}(x^2 - 4x + 2)$$

- b) Make the first three orthogonal polynomials with the Rodrigues formula $L_n(x) =$

$$\frac{e^x}{n!} \frac{d^n}{dx^n} (e^{-x} x^n). \text{ What are the normalization factors?}$$

$$L_0(x) = \frac{e^x}{0!} (e^{-x} x^0) = 1$$

$$L_1(x) = \frac{e^x}{1!} \frac{d}{dx} (e^{-x} x) = e^x (-e^{-x} x + e^{-x}) = 1 - x$$

$$L_2(x) = \frac{e^x}{2!} \frac{d^2}{dx^2} (e^{-x} x^2) = \frac{e^x}{2} \frac{d}{dx} (-e^{-x} x^2 + 2e^{-x} x) \\ = \frac{e^x}{2} (e^{-x} x^2 - 2e^{-x} x - 2e^{-x} x + 2e^{-x}) = \frac{1}{2}(x^2 - 4x + 2)$$

The Rodrigues formula is already giving normalized functions.

- c) Now consider the generating function $\varphi(x, t) = \frac{1}{1-t} e^{-\frac{xt}{1-t}} = \sum_{n=0}^\infty \frac{t^n}{n!} L_n(x)$. Following some of the steps that we did in class (differentiating this w.r.t. to x and t then peeling off expressions that result from grabbing everything in front of t^n), you should generate two equations that can then be manipulated to derive the differential equation for which the Laguerre polynomials are solutions, i.e. $xL_n''(x) + (1-x)L_n'(x) + nL_n(x) = 0$. Try this. Definitely get the two equations mentioned, and you can try to combine them to get the differential equation, but it can be quite tricky.

$$\frac{d\varphi}{dx} = -\frac{t}{1-t} \varphi \Rightarrow \sum \frac{t^n}{n!} L_n' = -\frac{t}{1-t} \sum \frac{t^n}{n!} L_n \Rightarrow \sum \frac{t^n}{n!} L_n' - \sum \frac{t^{n+1}}{n!} L_n' = -\sum \frac{t^{n+1}}{n!} L_n$$

$$t^n: \frac{1}{n!} L_n' - \frac{1}{(n-1)!} L_{n-1}' = -\frac{1}{(n-1)!} L_{n-1} \Rightarrow L_n' - nL_{n-1}' = -nL_{n-1} = \text{Eqn\#1}$$

$$\frac{d\varphi}{dt} = \frac{1-x-t}{1-2t+t^2} \varphi \Rightarrow \sum \frac{nt^{n-1}}{n!} L_n = \frac{1-x-t}{1-2t+t^2} \sum \frac{t^n}{n!} L_n$$

$$\Rightarrow \sum \frac{nt^{n-1}}{n!} L_n - 2 \sum \frac{t^n}{n!} L_n + \sum \frac{nt^{n+1}}{n!} L_n = \sum \frac{t^n}{n!} L_n - x \sum \frac{t^n}{n!} L_n - \sum \frac{t^{n+1}}{n!} L_n$$

$$t^n: \frac{n+1}{(n+1)!} L_{n+1} - 2 \frac{n}{n!} L_n + \frac{n-1}{(n-1)!} L_{n-1} = \frac{1}{n!} L_n - \frac{x}{n!} L_n - \frac{1}{(n-1)!} L_{n-1}$$

$$\Rightarrow L_{n+1} - 2nL_n + n(n-1)L_{n-1} = L_n - xL_n - nL_{n-1}$$

$$\Rightarrow L_{n+1} + (x - 2n - 1)L_n + n^2L_{n-1} = 0 = \text{Eqn\#2}$$

Start by taking Eqn#1 and shifting it from $n \rightarrow n + 1$

$$L_{n+1}' - (n+1)L_n' = -(n+1)L_n = \text{Eqn\#3}$$

and then taking the derivative of it:

$$L_{n+1}'' - (n+1)L_n'' = -(n+1)L_n' = \text{Eqn\#4}$$

Now shift the previous result from $n + 1 \rightarrow n + 2$

$$L''_{n+2} - (n + 2)L'_{n+1} = -(n + 2)L'_{n+1}$$

and now use Eqn#3 to replace the L'_{n+1} term leading to:

$$L''_{n+2} - (n + 2)L'_{n+1} + (n^2 + 3n + 2)L'_n - (n^2 + 3n + 2)L'_n = 0 \quad = \text{Eqn\#5}$$

Now use Eqn#2 and take the second derivative and bump it up to $n + 1 \rightarrow n + 2$

$$L''_{n+2} + (x - 2n - 3)L'_{n+1} + 2L'_{n+1} + (n + 1)^2 L''_n = 0$$

Now looking at it, realize that we can take Eqn#5 to replace L''_{n+2} in the preceding with

L''_{n+1}, L'_n, L_n . Then we can use Eqn#4 to replace all of the L'_{n+1} with L''_n, L'_n . And lastly we can use

Eqn#3 to replace the L'_{n+1} with L'_n, L_n . This gives everything in terms of L''_n, L'_n, L_n .

Doing so gives:

$$xL''_n + (1 - x)L'_n + nL_n = 0$$

2. Consider starting with an operator $L = (\alpha_0 x^2 + \alpha_1 x + \alpha_2) \frac{d^2}{dx^2} + (\beta_0 x + \beta_1) \frac{d}{dx}$. Use the conditions 1-3 from class to reduce this to a form such that $\alpha_0 \neq 0$ and the interval over which this is Hermitian is $[a, b]$. Determine the weight that would be used in the inner product in this case.

We want $\alpha(x) = (x - a)(x - b) = x^2 - (a + b)x + ab$ so that the roots are at $x = a$ and $x = b$.

Starting with $\alpha_0 x^2 + \alpha_1 x + \alpha_2$ we can rescale the overall polynomial with k , then shift the variable x by j , and finally rescale the newly shifted variable $x + j$ by m . The result is:

$$\begin{aligned} k\alpha_0(mx + mj)^2 + k\alpha_1(mx + mj) + k\alpha_2 \\ = (m^2 k\alpha_0)x^2 + (2m^2 k\alpha_0 j + mk\alpha_1)x + (m^2 k\alpha_0 j^2 + mk\alpha_1 j + k\alpha_2) \end{aligned}$$

We want this to equal $x^2 - (a + b)x + ab$, so pairing up coefficients of the same order in x we find:

$$\text{Eqn\#1: } m^2 k\alpha_0 = 1$$

$$\text{Eqn\#2: } 2m^2 k\alpha_0 j + mk\alpha_1 = -(a + b)$$

$$\text{Eqn\#3: } m^2 k\alpha_0 j^2 + mk\alpha_1 j + k\alpha_2 = ab$$

$$\text{Eqn\#1} \Rightarrow k = \frac{1}{\alpha_0 m^2}, \text{ inserted into Eqn\#2} \Rightarrow 2j + \frac{\alpha_1}{m\alpha_0} = -(a + b) \Rightarrow j = -\frac{(a+b)}{2} - \frac{\alpha_1}{2m\alpha_0}$$

Plugging the expressions for k, j into Eqn#3 gives:

$$m^2 = \frac{\alpha_1^2 - 4\alpha_2\alpha_0}{\alpha_0^2(a-b)^2} \Rightarrow m = \frac{\sqrt{\alpha_1^2 - 4\alpha_2\alpha_0}}{\alpha_0(a-b)} \Rightarrow k = \frac{\alpha_0(a-b)^2}{\alpha_1^2 - 4\alpha_2\alpha_0} \quad \text{and} \quad j = -\frac{(a+b)}{2} - \frac{\alpha_1}{2\alpha_0} \frac{\alpha_0(a-b)}{\sqrt{\alpha_1^2 - 4\alpha_2\alpha_0}}$$

Plugging these solutions in we find that $\alpha(x) = (x - a)(x - b)$ as needed.

To find $w(x)$ we first redefine $\beta_0 = q + p + 2$ and $\beta_1 = -qb - pa - b - a$ and then use:

$$w(x)\alpha(x) = C e^{\int \frac{\beta}{\alpha} dx} = C e^{\int \left(\frac{q+1}{x-a} + \frac{p+1}{x-b} \right) dx} = C e^{(q+1)\ln(x-a) + (p+1)\ln(x-b)} = C(x-a)^{q+1}(x-b)^{p+1}$$

$$w(x) = C(x-a)^q(x-b)^p$$

3. Find an expression for the Fourier transform of a product of three transformable functions $f_1(y), f_2(y), f_3(y)$ in terms of their transforms $g_1(k), g_2(k), g_3(k)$.

$$\begin{aligned}
 G(k) &= \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} f_1(y) f_2(y) f_3(y) e^{-iky} dy \\
 &= \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} \left(\frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} g_1(k') e^{ik'y} dk' \right) f_2(y) f_3(y) e^{-iky} dy \\
 &= \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} g_1(k') \left(\frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} f_2(y) f_3(y) e^{ik'y -iky} dy \right) dk' \\
 &= \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} g_1(k') \left(\frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} f_2(y) f_3(y) e^{-ik''y} dy \right) dk' \quad \text{where } k'' = k - k' \\
 &= \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} g_1(k') \left(\frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} g_2(k''') g_3(k'' - k''') dk'' \right) dk' \\
 &= \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} g_1(k') g_2(k''') g_3(k - k' - k''') dk'' dk'
 \end{aligned}$$

4. Using the result of problem 1, evaluate the Fourier transform of the product of the three functions $f_1(y) = e^{ik_1y}, f_2(y) = e^{ik_2y}$ and $f_3(y) = e^{ik_3y}$. Verify that your answer makes sense by considering the product as a single function.

$$\text{First of all } g_i(k) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} f_i(y) e^{-iky} dy = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} e^{i(k_i - k)y} dy = \sqrt{2\pi} \delta(k_i - k)$$

$$\begin{aligned}
 G(k) &= \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} e^{k_1y} e^{k_2y} e^{k_3y} e^{-iky} dy \\
 &= \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \sqrt{2\pi} \delta(k_1 - k') \sqrt{2\pi} \delta(k_2 - k''') \sqrt{2\pi} \delta(k_3 - k + k' + k''') dk'' dk' \\
 &= 2\pi \delta(k_3 - k + k_1 + k_2) = 2\pi \delta(k_1 + k_2 + k_3 - k)
 \end{aligned}$$

Alternatively,

$$g(k) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} e^{i(k_1 + k_2 + k_3)y} e^{-iky} dy = 2\pi \delta(k_1 + k_2 + k_3 - k) \quad \text{as expected.}$$

5. Find Y_{20} by Gram-Schmidting.

$$\text{For } l = 2 \text{ and } m = 0 \text{ we have } f_{20}(\cos \theta) = \bar{Y}_{20} = A + B \cos \theta + C \cos^2 \theta.$$

$$\text{Then } Y_{20} = \frac{\bar{Y}_{20} - Y_{00}(Y_{00}, \bar{Y}_{20}) - Y_{10}(Y_{10}, \bar{Y}_{20}) - Y_{1-1}(Y_{1-1}, \bar{Y}_{20}) - Y_{11}(Y_{11}, \bar{Y}_{20})}{\|\bar{Y}_{20} - Y_{00}(Y_{00}, \bar{Y}_{20}) - Y_{10}(Y_{10}, \bar{Y}_{20}) - Y_{1-1}(Y_{1-1}, \bar{Y}_{20}) - Y_{11}(Y_{11}, \bar{Y}_{20})\|}$$

Doing these separately and using that:

$$\int_0^\pi \sin \theta \cos^m \theta d\theta = -\frac{1}{m+1} (\cos^{m+1} \pi - 1)$$

$$\int_0^\pi \cos^m \theta d\theta = \frac{m-1}{m} \int_0^\pi \cos^{m-2} \theta d\theta \quad \text{for } n > 1$$

$$\int_0^{2\pi} e^{\pm i\varphi} d\varphi = 0$$

$$Y_{00}(Y_{00}, \bar{Y}_{20}) = \frac{1}{2\sqrt{\pi}} \int_0^{2\pi} \int_0^\pi \frac{1}{2\sqrt{\pi}} \sin \theta (A + B \cos \theta + C \cos^2 \theta) d\theta d\varphi$$

$$= \frac{2\pi}{4\pi} \left(\int_0^\pi [A \sin \theta + B \sin \theta \cos \theta + C \sin \theta \cos^2 \theta] d\theta \right)$$

$$= \frac{1}{2} \left(2A + 0 + \frac{2}{3} C \right) = A + \frac{1}{3} C$$

$$Y_{10}(Y_{10}, \bar{Y}_{20}) = \frac{\sqrt{3}}{2\sqrt{\pi}} \cos \theta \int_0^{2\pi} \int_0^\pi \frac{\sqrt{3}}{2\sqrt{\pi}} \sin \theta \cos \theta (A + B \cos \theta + C \cos^2 \theta) d\theta d\varphi$$

$$= \frac{6\pi}{4\pi} \cos \theta \left(\int_0^\pi [A \sin \theta \cos \theta + B \sin \theta \cos^2 \theta + C \sin \theta \cos^3 \theta] d\theta \right)$$

$$= \frac{3}{2} \cos \theta \left(0 + \frac{2}{3} B + 0 \right) = B \cos \theta$$

$$Y_{1-1}(Y_{1-1}, \bar{Y}_{20}) = \frac{\sqrt{3}}{2\sqrt{2\pi}} e^{-i\varphi} \sin \theta \int_0^{2\pi} \int_0^\pi \frac{\sqrt{3}}{2\sqrt{2\pi}} e^{i\varphi} \sin^2 \theta (A + B \cos \theta + C \cos^2 \theta) d\theta d\varphi$$

$$= \frac{3}{8\pi} e^{-i\varphi} \sin \theta \left(\int_0^{2\pi} e^{i\varphi} d\varphi \int_0^\pi [A \sin^2 \theta + B \sin^2 \theta \cos \theta + C \sin^2 \theta \cos^2 \theta] d\theta \right)$$

$$= 0$$

$$Y_{11}(Y_{11}, \bar{Y}_{20}) = -\frac{\sqrt{3}}{2\sqrt{2\pi}} e^{i\varphi} \sin \theta \int_0^{2\pi} \int_0^\pi -\frac{\sqrt{3}}{2\sqrt{2\pi}} e^{-i\varphi} \sin^2 \theta (A + B \cos \theta + C \cos^2 \theta) d\theta d\varphi$$

$$= \frac{3}{8\pi} e^{i\varphi} \sin \theta \left(\int_0^{2\pi} e^{-i\varphi} d\varphi \int_0^\pi [A \sin^2 \theta + B \sin^2 \theta \cos \theta + C \sin^2 \theta \cos^2 \theta] d\theta \right)$$

$$= 0$$

Finally:

$$Y_{20} = \frac{A+B \cos \theta + C \cos^2 \theta - A - \frac{1}{3}C - B \cos \theta}{\left\| A+B \cos \theta + C \cos^2 \theta - A - \frac{1}{3}C - B \cos \theta \right\|} = \frac{\cos^2 \theta - \frac{1}{3}}{\left\| \cos^2 \theta - \frac{1}{3} \right\|} = \frac{\cos^2 \theta - \frac{1}{3}}{\sqrt{\int_0^{2\pi} \int_0^\pi \sin \theta \left(\cos^2 \theta - \frac{1}{3} \right)^2 d\theta d\varphi}} = \sqrt{\frac{45}{16\pi}} \left(\cos^2 \theta - \frac{1}{3} \right)$$

6. Find Y_{32} using whatever method you want.

We can Rodrigues it to find:

$$Y_{32}(\theta, \varphi) = (-1)^2 \left[\frac{7}{4\pi} \frac{1!}{5!} \right]^{\frac{1}{2}} P_3^2(\cos \theta) e^{i2\varphi}$$

$$\text{Where } P_3^2(x) = (1-x^2) \frac{d^2}{dx^2} P_3(x) = (1-x^2) \frac{d^2}{dx^2} \left[\frac{1}{2}(5x^3 - 3x) \right] = 15(x - x^3)$$

$$\text{Then } Y_{32}(\theta, \varphi) = 15 \left[\frac{7}{480\pi} \right]^{\frac{1}{2}} (\cos \theta - \cos^3 \theta) e^{i2\varphi} = \frac{1}{4} \sqrt{\frac{105}{2\pi}} \sin^2 \theta \cos \theta e^{i2\varphi}$$

7. Evaluate the Stieltjes integral of $f(x) = e^{-x}$ with the measure inducing function given by $g(x) = n$ for $n \leq x < n + 1$ where $n \in \mathbb{Z}$ (integers that is) over $x \in [0, \infty]$.

$$\int_0^{\infty} f(x) dg(x) = \lim_{x_{i+1}-x_i \rightarrow 0} \sum_{i=0}^{\infty} f(\bar{x}_i) [g(x_{i+1}) - g(x_i)] = \sum_{i=0}^{\infty} e^{-i} = 1 + \frac{1}{e-1} = \frac{e}{e-1}$$

8. Verify that the resolution of the identity for the position operator X , i.e. $Xf(x) = xf(x)$, is given by

$$E(\mu)f(x) = \begin{cases} f(x) & x \leq \mu \\ 0 & x > \mu \end{cases}.$$

First we show that $E(\mu)$ satisfies the usual requirements:

Obviously $E(-\infty) = 0$ since any $x > -\infty$, and $E(\infty) = I$ since any $x \leq \infty$.

Now we need to show that $E(\mu_1)E(\mu_2) = E(\mu_1)$ is $\mu_1 < \mu_2$:

$$E(\mu_1)E(\mu_2)f(x) = 0 = E(\mu_1)f(x) \text{ for } \mu_1, \mu_2 < x$$

$$E(\mu_1)E(\mu_2)f(x) = 0 = E(\mu_1)f(x) \text{ for } \mu_1 < x < \mu_2$$

$$E(\mu_1)E(\mu_2)f(x) = f(x) = E(\mu_1)f(x) \text{ for } \mu_1, \mu_2 > x$$

Finally, $\int_{-\infty}^{\infty} dE(\mu) f(x) = \lim_{\Delta \rightarrow 0} \sum_{i=0}^{\infty} [E(\mu_i + \Delta) - E(\mu_i)] f(x)$. Now for each x , only one value of i will give $E(\mu_i + \Delta) = I$ while $E(\mu_i) = 0$, and it is when $\mu_i = x$. But this means that for each value of x , we get that this is acting as the identity at that value, but it works for any value of x , i.e. $\int_{-\infty}^{\infty} dE(\mu) f(x) = If(x)$.

Now we should show that its action is $[\int_{-\infty}^{\infty} \mu dE(\mu)]f(x) = xf(x)$, but using the interpretation above, it should be obvious that:

$$[\int_{-\infty}^{\infty} \mu dE(\mu)]f(x) = xf(x), \text{ i.e. } [\int_{-\infty}^{\infty} \mu dE(\mu)] = X.$$

9. Given that $E_A(\lambda)$ is the resolution of the identity for the operator A . Show that $E_A(\lambda_2) - E_A(\lambda_1) = [E_A(\lambda_2) - E_A(\lambda_1)]^2$ for $\lambda_2 > \lambda_1$ but not for $\lambda_1 > \lambda_2$.

$$\begin{aligned} [E_A(\lambda_2) - E_A(\lambda_1)]^2 &= E_A(\lambda_2)^2 - E_A(\lambda_2)E_A(\lambda_1) - E_A(\lambda_1)E_A(\lambda_2) + E_A(\lambda_1)^2 \\ &= E_A(\lambda_2) - E_A(\lambda_1) - E_A(\lambda_1) + E_A(\lambda_1) = E_A(\lambda_2) - E_A(\lambda_1) \end{aligned}$$

Note that this doesn't work when $\lambda_1 > \lambda_2$, i. e.

$$\begin{aligned} [E_A(\lambda_2) - E_A(\lambda_1)]^2 &= E_A(\lambda_2)^2 - E_A(\lambda_2)E_A(\lambda_1) - E_A(\lambda_1)E_A(\lambda_2) + E_A(\lambda_1)^2 \\ &= E_A(\lambda_2) - E_A(\lambda_2) - E_A(\lambda_2) + E_A(\lambda_1) = -E_A(\lambda_2) + E_A(\lambda_1) \neq E_A(\lambda_2) - E_A(\lambda_1) \end{aligned}$$

10. Consider the quantum-mechanical observables L_x, L_y and L_z , which are represented as matrices as follows:

$$L_x = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}, \quad L_y = \frac{1}{\sqrt{2}} \begin{pmatrix} 0 & -i & 0 \\ i & 0 & -i \\ 0 & i & 0 \end{pmatrix}, \quad L_z = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -1 \end{pmatrix}$$

The Hamiltonian for this system has the form $H = H_0 + L_z$ where H_0 is time-independent and commutes with L_x, L_y and L_z .

a) Suppose that at $t = 0$ we have prepared the system in an eigenstate of L_z , namely, the state belonging to the eigenvalues $m = +1$ of L_z . If we measure L_z at a later time $t = T$, what are the probabilities that we will find the values $+1, 0$ or -1 .

Let's start with the eigens of L_z :

$$\det(L_z - \lambda I) = \det \begin{pmatrix} 1 - \lambda & 0 & 0 \\ 0 & -\lambda & 0 \\ 0 & 0 & -1 - \lambda \end{pmatrix} = 0 \Rightarrow \lambda_1 = 1, \lambda_2 = 0, \lambda_3 = -1$$

$$L_z \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} a \\ 0 \\ -c \end{pmatrix} = \lambda_1 \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} a \\ b \\ c \end{pmatrix} \Rightarrow v_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

$$L_z \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} a \\ 0 \\ -c \end{pmatrix} = \lambda_2 \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \Rightarrow v_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}$$

$$L_z \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} a \\ 0 \\ -c \end{pmatrix} = \lambda_3 \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} -a \\ -b \\ -c \end{pmatrix} \Rightarrow v_3 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

Since H_0 is time-independent, we know that since $[H_0 + L_z, L_z] = 0$, then the probabilities of the results of measurement of L_z do not change with time. But since we are starting at $t = 0$ in the state v_1 with $\lambda = \lambda_1 = +1$, then this will have 100% probability at time $t = T$, and the probability of getting 0 or -1 as the results is zero.

b) Suppose instead that we measure L_x at time $t = T$. What are the possible values of L_x that can be obtained and what are their probabilities?

First of all, note that $[H_0 + L_z, L_z] = 0$ then measuring L_z at $t = 0$ and getting v_1 means it will remain in this state unless and until we make another measurement. If we make a measurement of L_x at time $t = T$, it is just like measuring L_x for an eigenstate of L_z .

First the L_x eigen story is:

$$\det(L_x - \lambda'I) = \det \begin{pmatrix} -\lambda' & \frac{1}{\sqrt{2}} & 0 \\ \frac{1}{\sqrt{2}} & -\lambda' & \frac{1}{\sqrt{2}} \\ 0 & \frac{1}{\sqrt{2}} & -\lambda' \end{pmatrix} = -\lambda' \left(\lambda'^2 - \frac{1}{2} \right) + \frac{1}{2} \lambda' = 0 \Rightarrow \lambda'_1 = 1, \lambda'_2 = 0, \lambda'_3 = -1$$

$$L_x \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} \frac{1}{\sqrt{2}} b \\ \frac{1}{\sqrt{2}} a + \frac{1}{\sqrt{2}} c \\ \frac{1}{\sqrt{2}} b \end{pmatrix} = \lambda'_1 \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} a \\ b \\ c \end{pmatrix} \Rightarrow v'_1 = \begin{pmatrix} \frac{1}{2} \\ \frac{1}{\sqrt{2}} \\ \frac{1}{2} \end{pmatrix}$$

$$L_x \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} \frac{1}{\sqrt{2}} b \\ \frac{1}{\sqrt{2}} a + \frac{1}{\sqrt{2}} c \\ \frac{1}{\sqrt{2}} b \end{pmatrix} = \lambda'_2 \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} \Rightarrow v'_2 = \begin{pmatrix} \frac{1}{\sqrt{2}} \\ 0 \\ -\frac{1}{\sqrt{2}} \end{pmatrix}$$

$$L_x \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} \frac{1}{\sqrt{2}} b \\ \frac{1}{\sqrt{2}} a + \frac{1}{\sqrt{2}} c \\ \frac{1}{\sqrt{2}} b \end{pmatrix} = \lambda'_3 \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} -a \\ -b \\ -c \end{pmatrix} \Rightarrow v'_3 = \begin{pmatrix} \frac{1}{2} \\ -\frac{1}{\sqrt{2}} \\ \frac{1}{2} \end{pmatrix}$$

To determine the probabilities of getting each of these L_x eigenvalues as a result of a measurement done on a system in the state v_1 , we can simply use:

$$P(\lambda'_i) = |(v'_i, v_1)|^2 \Rightarrow P(\lambda'_1) = |(v'_1, v_1)|^2 = \frac{1}{4}, P(\lambda'_2) = |(v'_2, v_1)|^2 = \frac{1}{2}, P(\lambda'_3) = |(v'_3, v_1)|^2 = \frac{1}{4}$$

Which of course satisfy $\sum_i P_i = 1$.